



Size and Location Matter: a New Baseline for Salient Object Detection

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Research

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Overview

We propose a new baseline method for saliency detection. It simply considers a large region close to the image center as salient, and defines the saliency of a region i as the product of its size $A(i)$ and centerness $C(i)$: $S = C(i) \times \sqrt{A(i)}$. As accurate image segmentation problem is difficult, a novel geodesic filtering framework is presented to estimate these attributes in a soft manner, without hard image segmentation.

Advantages

- 1) Concepts are simple and intuitive
- 2) A strong baseline method achieves very competitive results
- 3) Highly complementary with the state-of-the-art
- 4) Fast, easy to implement

Geodesic Connectivity and Filtering

Geodesic Connectivity

- 1) Construct a superpixel [1] graph
- 2) Compute the pair-wise shortest paths $dist$
- 3) Geodesic connectivity between i, j :

$$con(i, j) = \exp\left(\frac{-dist(i, j)^2}{2\sigma^2}\right) \in [0, 1]$$

Geodesic connectivity is a continuous measure of how well any two superpixels are spatially connected. A superpixel only has large connectivity values (near 1) for ones in the same homogeneous region, and has near 0 values for the others.

Geodesic Filtering

A smoothing process using geodesic connectivity, which is useful to compute region properties in a soft manner:

$$\widetilde{GF} = \sum_{j=1}^N con(i, j) \times M(j)$$

$$GF(M, i) = \frac{\widetilde{GF}}{\sum_{j=1}^N con(i, j)}$$

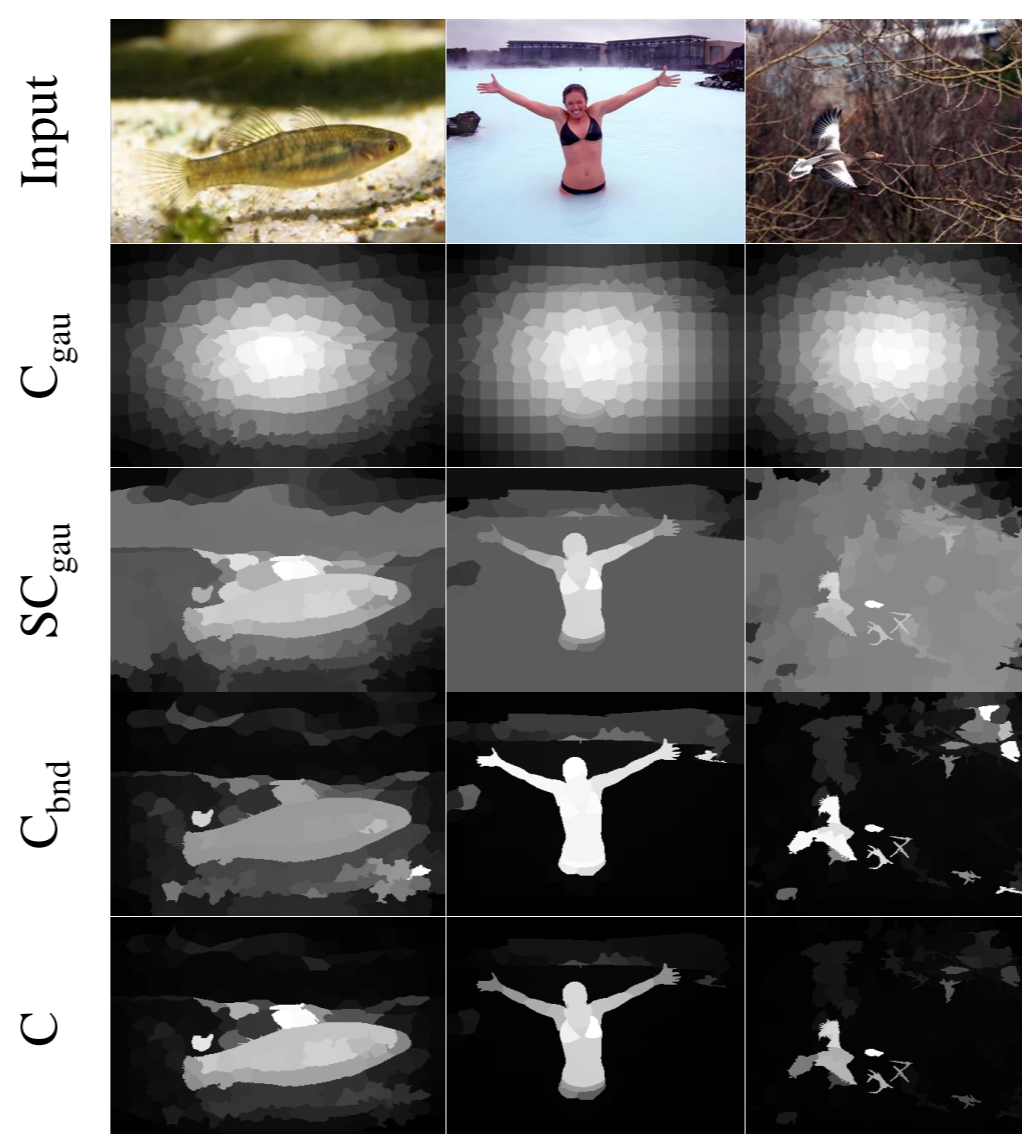
where N is the number of superpixels, and $M(i)$ is the region property value of superpixel i

Advantages

- 1) Without hard image segmentation
- 2) Produce stable results with easy-to-set parameters

Computation of Region Centerness and Size

Adaptive Computation of Region Centerness



In order to make centerness map to be highly adaptive to the image content, and suitable for both off-center and multiple objects, our final centerness map is defined as: $C = SC_{gau} \times C_{bnd}$

- 1) Use GF to “smooth” naive Gaussian fall-off map C_{gau} : $SC_{gau} = GF(C_{gau})$

- 2) Compute C_{bnd} to suppress large background regions, which always touch different sides of the image boundary:

$$C_{bnd}(i) = \sqrt[4]{L(i) \times T(i) \times R(i) \times B(i)}$$

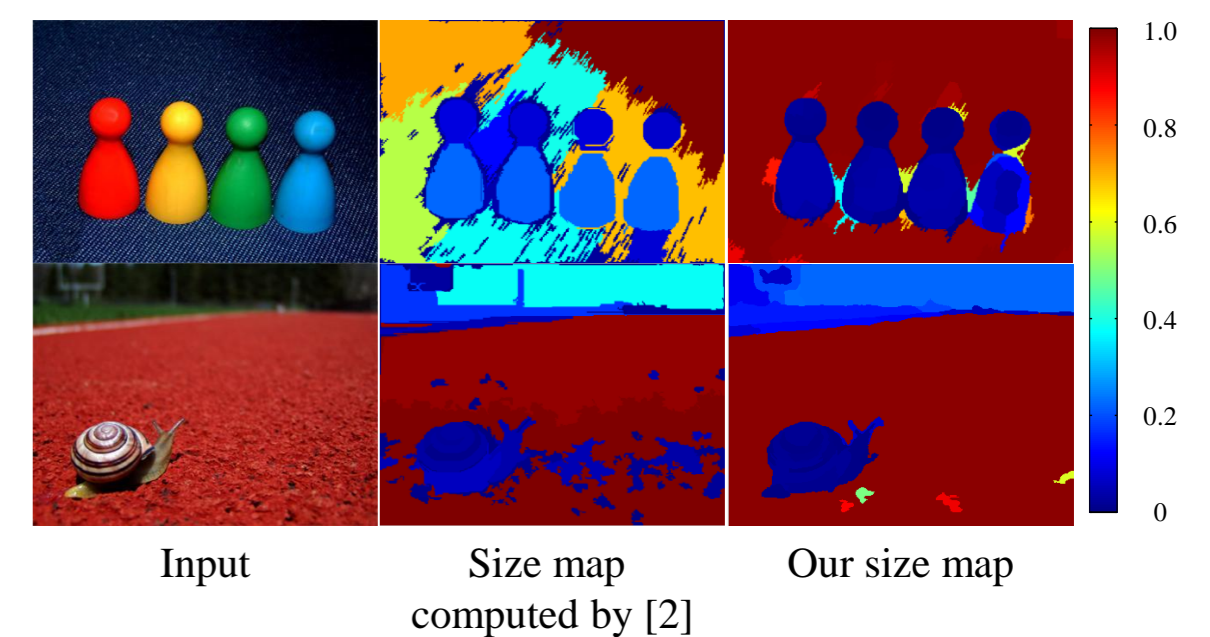
where $L(i)$, $T(i)$, $R(i)$, $B(i)$ are the geodesic distances of superpixel i to the left, top, right, and bottom boundaries of the image

Approximate Computation of Region Size

We count the number of superpixels (of similar sizes and shapes) in a homogeneous region to approximate size of the region. \widetilde{GF} can be used to “sum” all superpixels in the same homogeneous region softly, producing more stable results than hard segmentation methods (such as [2]):

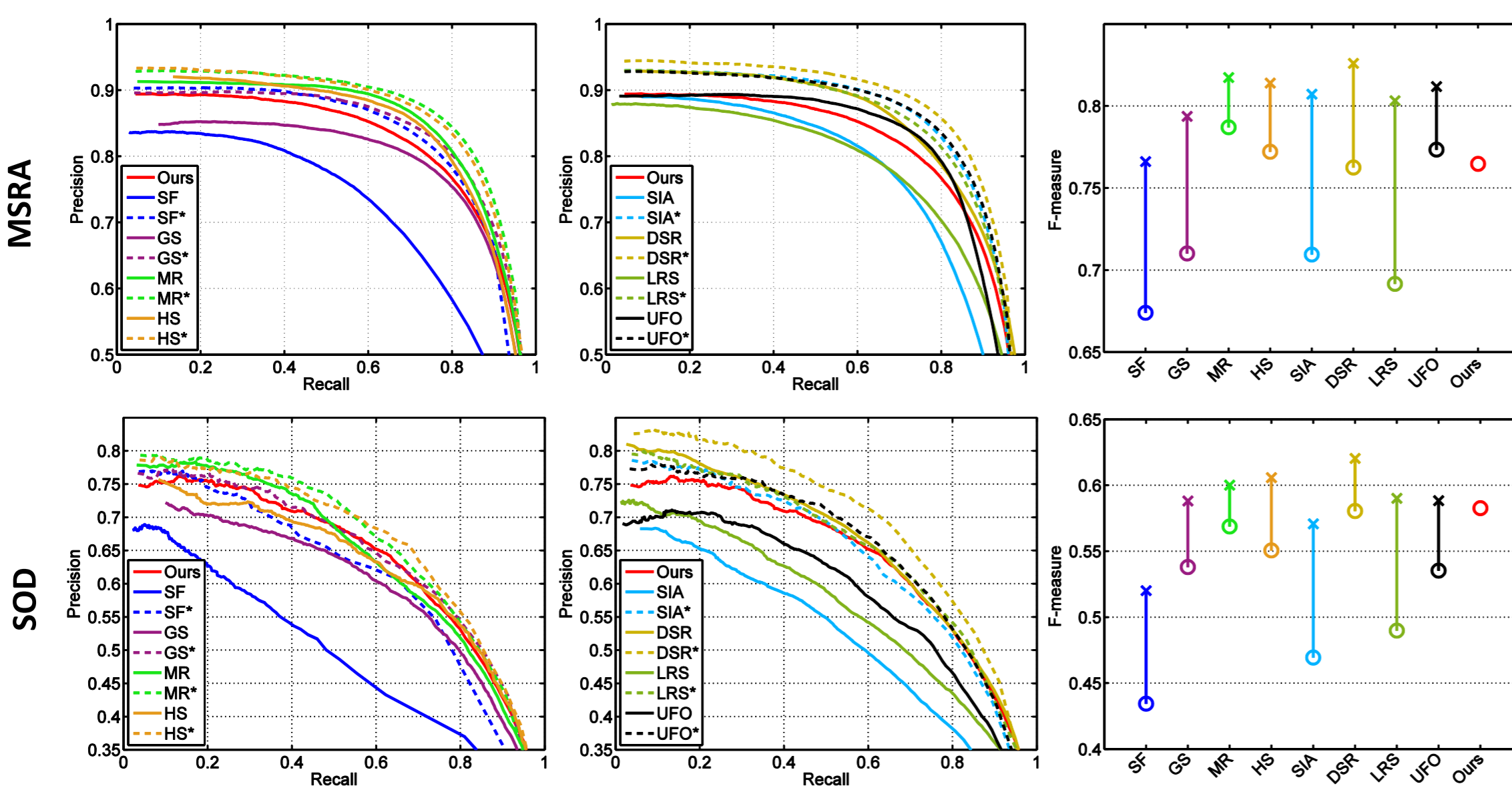
$$A = \widetilde{GF}(U)$$

where U is a uniform map that has the same normalized area for all the superpixels



Experiments

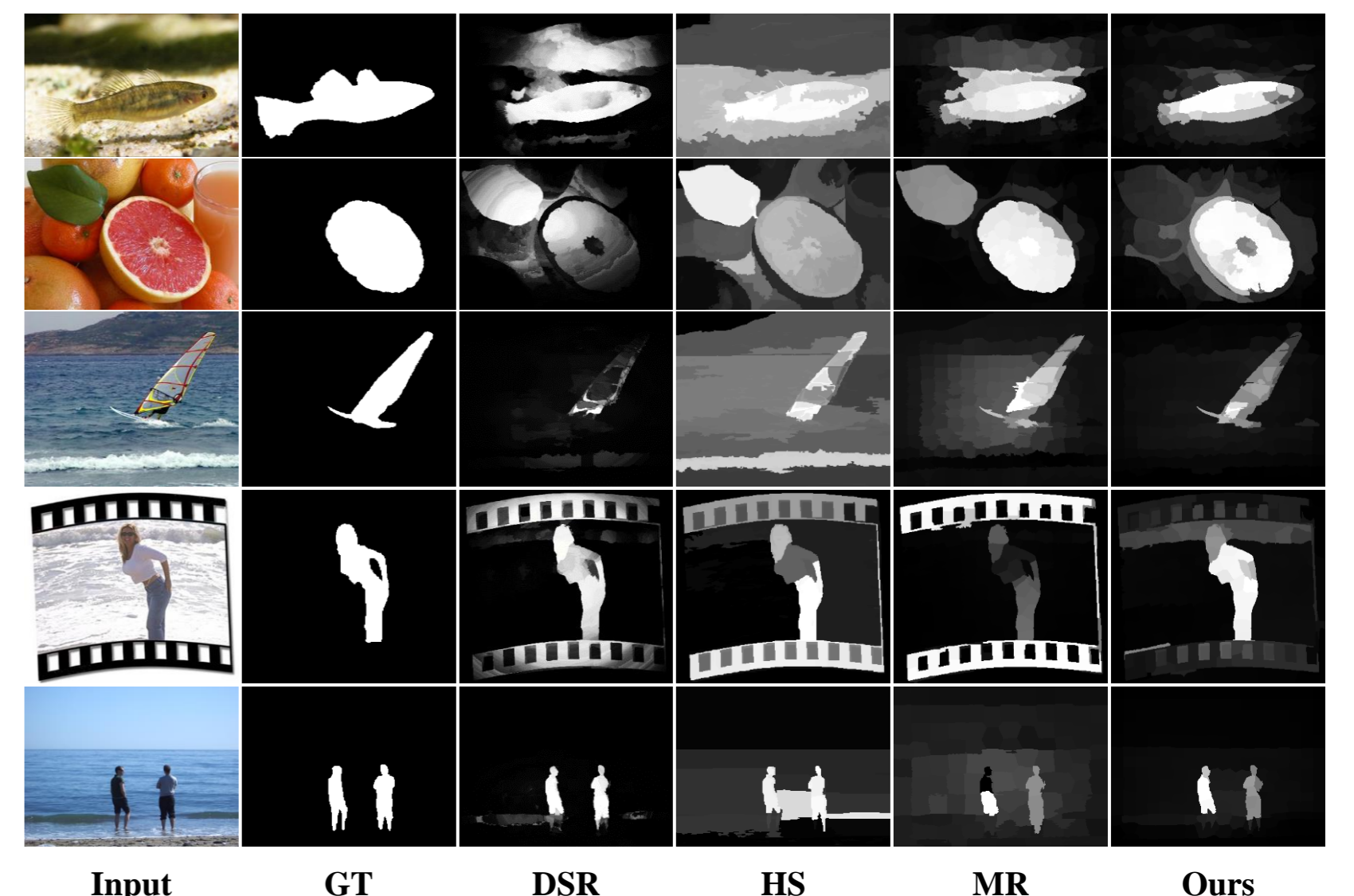
Performance evaluation



X^* means combining the X method with ours, by multiplying the two saliency maps

- 1) Our method compares favorably with previous works
- 2) Ours outperforms state-of-the-art on more difficult datasets (SOD)
- 3) After combination, all previous methods are significantly improved
- 4) Performance gaps between previous methods are smaller after combination

Examples



References

- [1] SLIC superpixels. PAMI 2012.
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- [4] (HS) Hierarchical Saliency Detection. CVPR 2013.
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- [6] (SIA) Efficient Salient Region Detection with Soft Image Abstraction. ICCV2013
- [7] (GS) Geodesic Saliency Using Background Priors. ECCV 2012.
- [8] (SF) Saliency Filters: Contrast based Filtering for Salient Region Detection. CVPR 2012.
- [9] (LRS) A Unified Approach to Salient Object Detection via Low Rank Matrix Recovery. CVPR 2012.
- [10] (UFO) Salient Region Detection by UFO: Uniqueness, Focusness and Objectness. ICCV 2013.